

Towards a Scalable Online Hierarchical Clustering Algorithm

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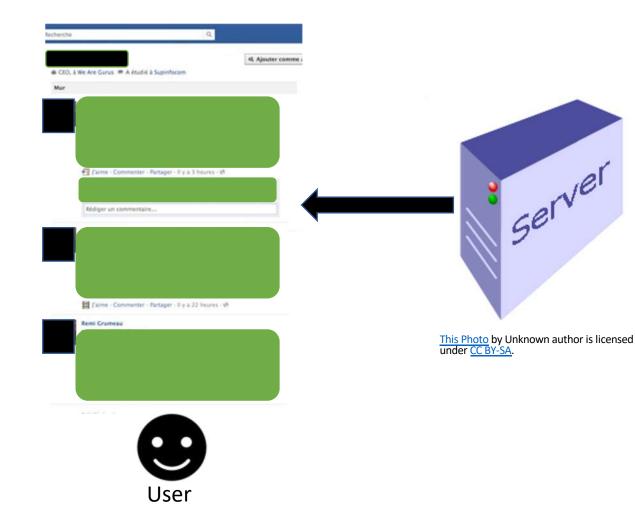


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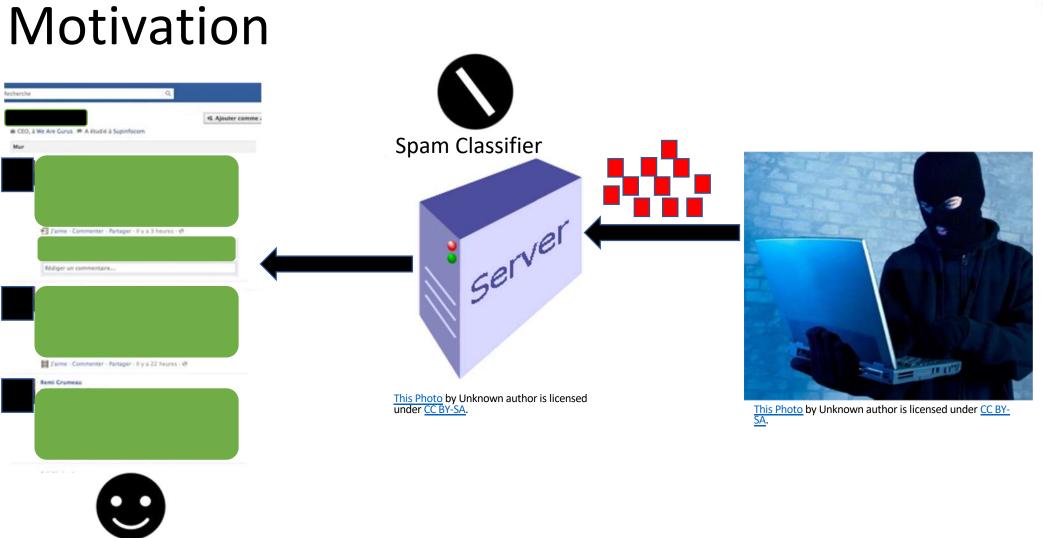
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- Our Contributions
- Hierarchical Clustering
- Online Hierarchical Clustering
- Online Eigenvector Updates
- Conclusion





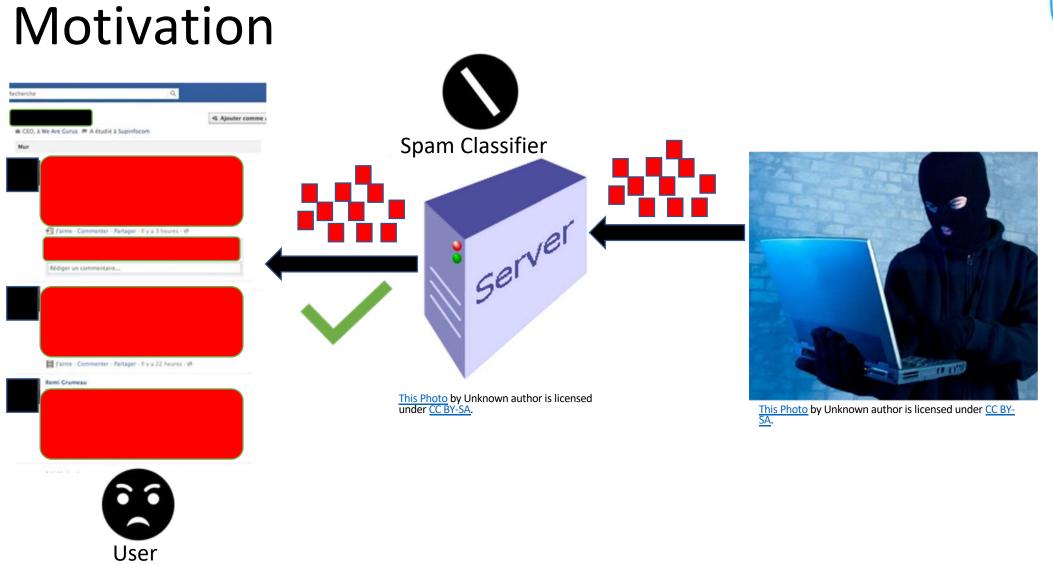






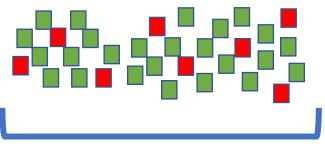
User









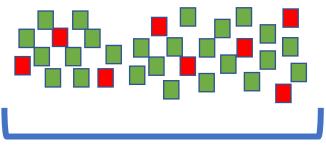


1 microsecond



= 100 comments



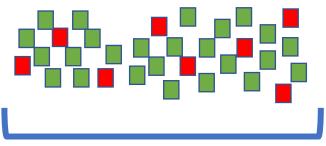


1 microsecond

- = 100 comments
- = 100 comments

• Feasible to get labels for all incoming data?





1 microsecond

= 100 comments

= 100 comments

- Feasible to get labels for all incoming data?
- Can we afford delay in identification of harmful data?

May be and the second s

Requirements

- Unsupervised
- Real-time identification
- Incremental updates to the model



- Suspicious and malicious content may have a subtype-supertype relationship
- For example:
 - Harassment Spam
 - Bullying abusive, rumors
 - Profanity expletives, crude language
 - Trolling
 - Threats blackmail, threats to life
 - Scam
 - Money scam
 - Malware downloads
 - Phishing

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Requirements

- Unsupervised
- Real-time classification
- Incremental updates to the model
- Potentially use the subtype-supertype relationship

Possible Solutions



- Support Vector Machines
- ✓ Fast querying

X No subtype-supertype relation usage, no incremental updates, supervised

Possible Solutions



- Support Vector Machines
- ✓ Fast querying

X No subtype-supertype relation usage, no incremental updates, supervised

- Flat clustering
- Unsupervised, fast querying

X No subtype-supertype relation usage, no incremental updates

Possible Solutions



- Support Vector Machines
 - Fast querying
- X No subtype-supertype relation usage, no incremental updates, supervised
- Flat clustering
- Unsupervised, fast querying
- X No subtype-supertype relation usage, no incremental updates
- Online flat clustering
 - Unsupervised, fast querying, incremental updates
- X No subtype-supertype relation usage

Proposed Solutions



• Hierarchical Clustering

Unsupervised, fast querying, subtype-supertype relation usage

X No incremental updates

Proposed Solutions



• Hierarchical Clustering

Unsupervised, fast querying, subtype-supertype relation usage

× No incremental updates

• Online Hierarchical Clustering

Unsupervised, fast querying, subtype-supertype relation usage, incremental updates

Our Contributions



- Practically efficient Hierarchical Clustering with guarantees on the quality of solution produced
- Demonstration of use of Hierarchical Clustering for
 - Real Time Classification
 - Anomaly detection
- Heuristics for Online Hierarchical Clustering
- Algorithm for Online Eigenvector Updates in a Dynamic Stream

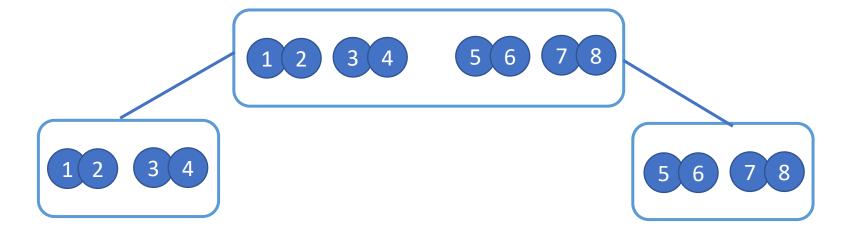


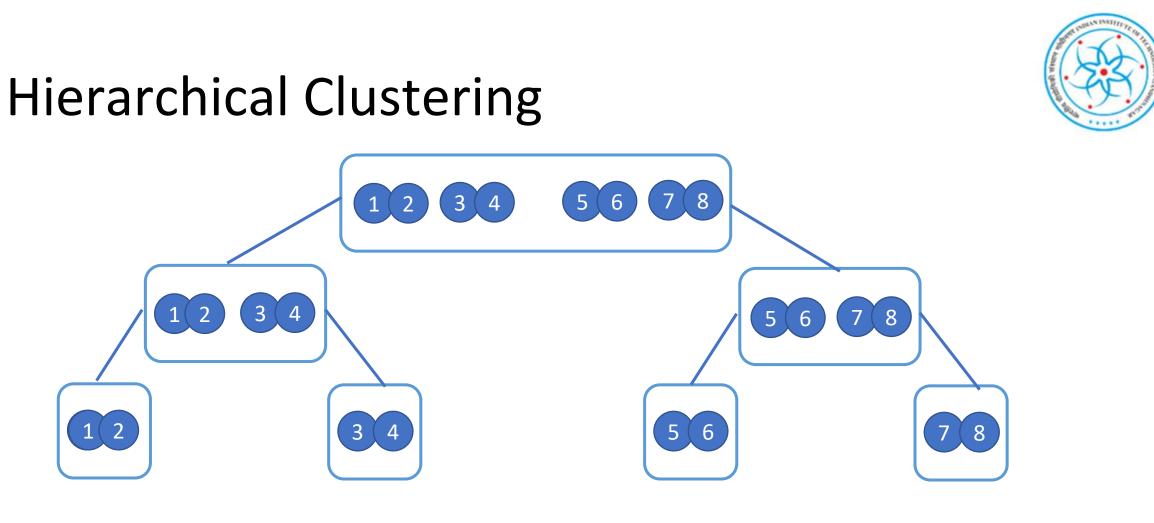
Hierarchical Clustering

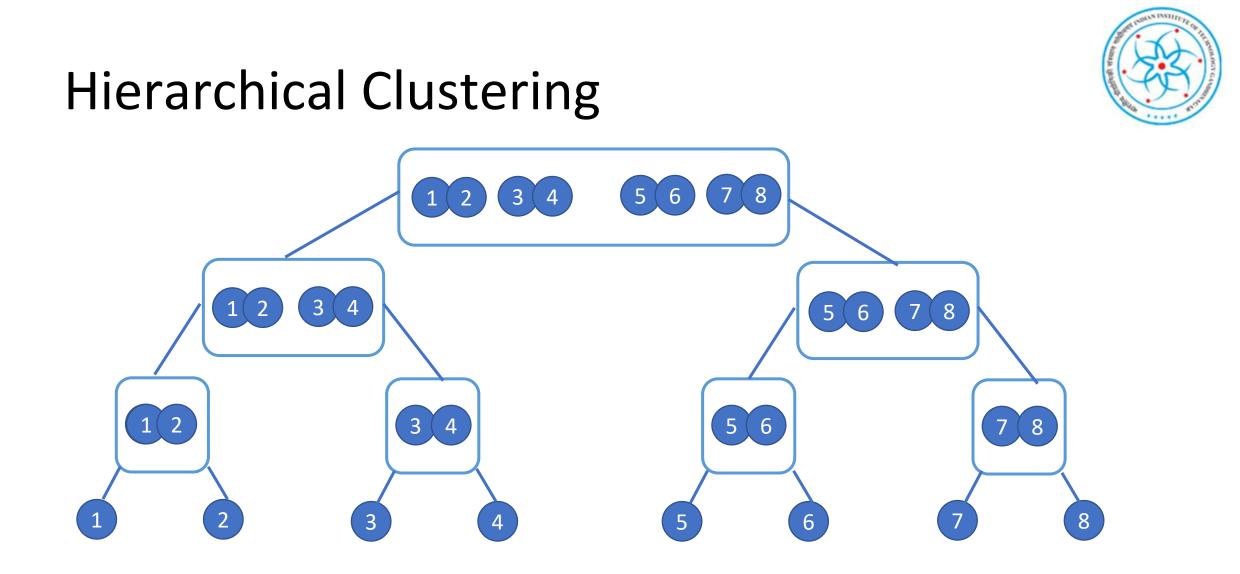


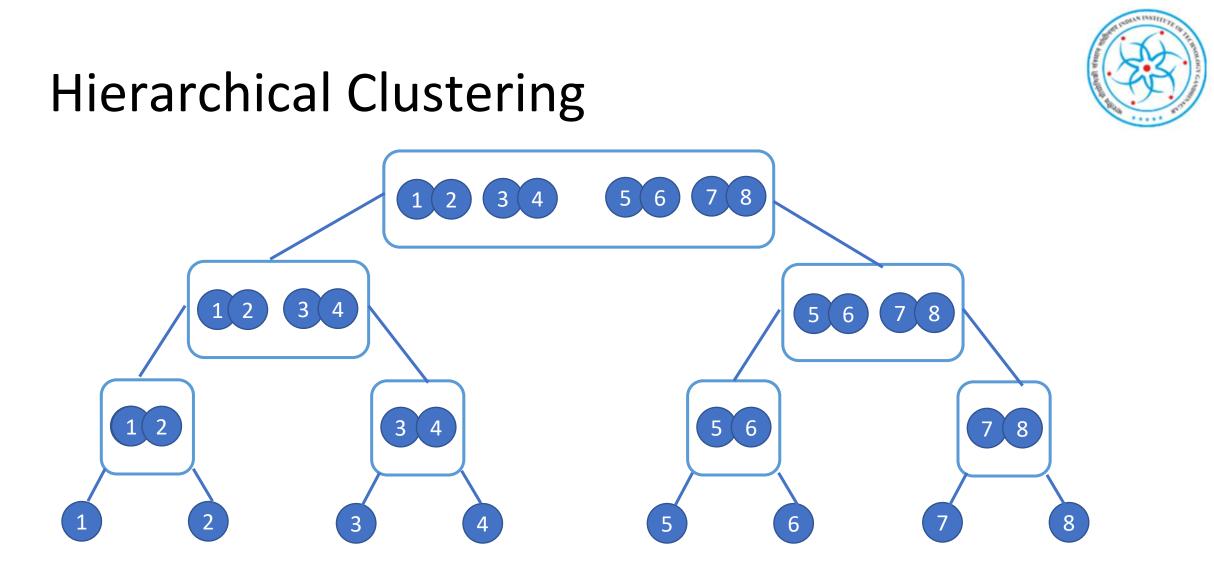


Hierarchical Clustering









How do you measure the Quality? How is the splitting performed?

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Objective Function

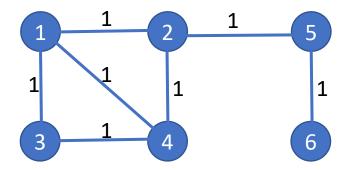
$$cost_{\mathcal{G}}(\mathcal{T}) = \sum_{(i,j)\in\mathcal{E}} w_{ij} |leaves(i \lor j)|$$

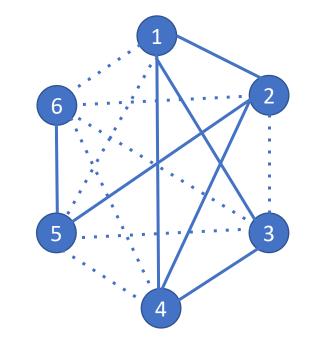
Where, \mathcal{T} is a rooted hierarchical clustering tree for graph \mathcal{G} , $leaves(\mathcal{T})$ are the nodes of \mathcal{G} , $i \lor j$ denotes the *least common ancestor* of i, j in \mathcal{T} , w_{ij} denotes the similarity between nodes i and j, and $|leaves(\mathcal{N})|$ denote the number of leaves in the subtree rooted at \mathcal{N} .

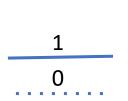
$$cost_{\mathcal{G}}(\mathcal{T}^*) = min_{\mathcal{T}} cost_{\mathcal{G}}(\mathcal{T})$$

[1] Dasgupta, S. (2015). A cost function for similarity-based hierarchical clustering. arXiv preprint arXiv:1510.05043.



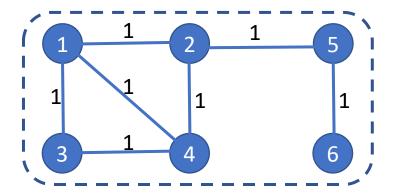




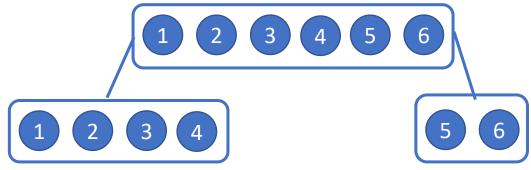


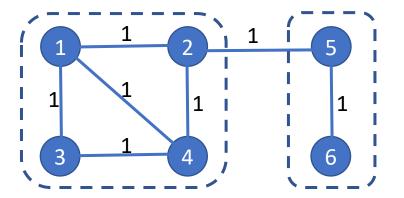












Edges split: (2,5) Weight of the edge (2,5): 1

Number of nodes in cluster: 6

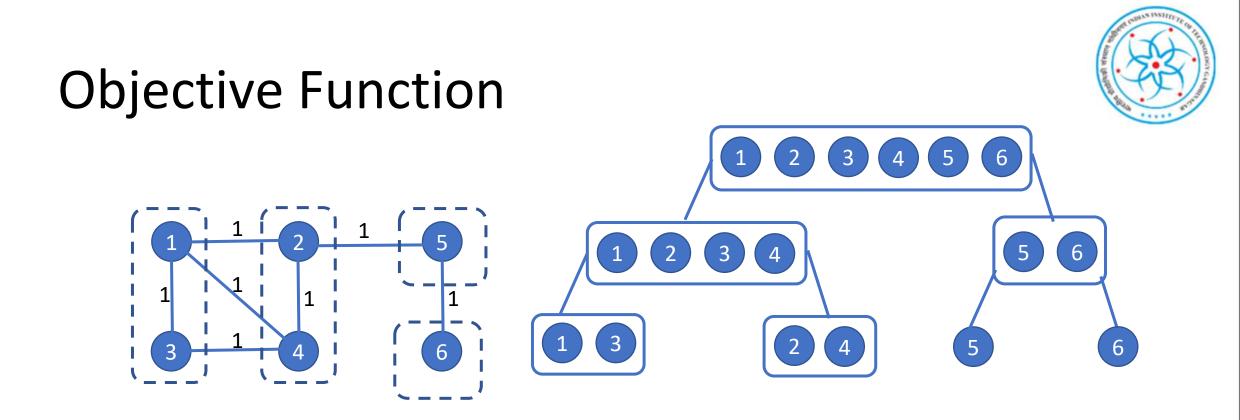
Cost: 1x6 = 6Total Cost = 6



Edges split: (1,2), (1,4), (3,4) Weight of the edge (1,2): 1 Weight of the edge (1,4): 1 Weight of the edge (3,4): 1

Number of nodes in cluster: 4

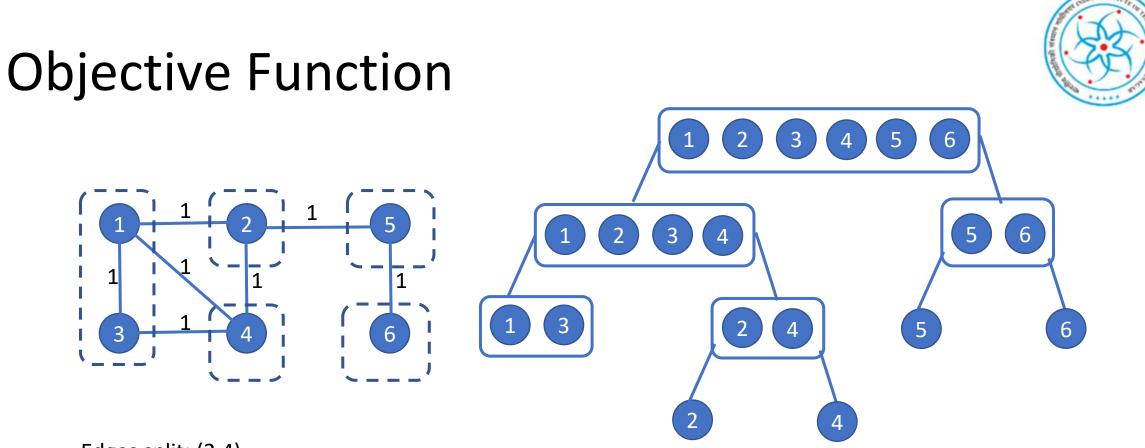
Cost: (1+1+1) x 4 = 12 Total Cost = 6 + 12 = 18



Edges split: (5,6) Weight of the edge (5,6): 1

Number of nodes in cluster: 2

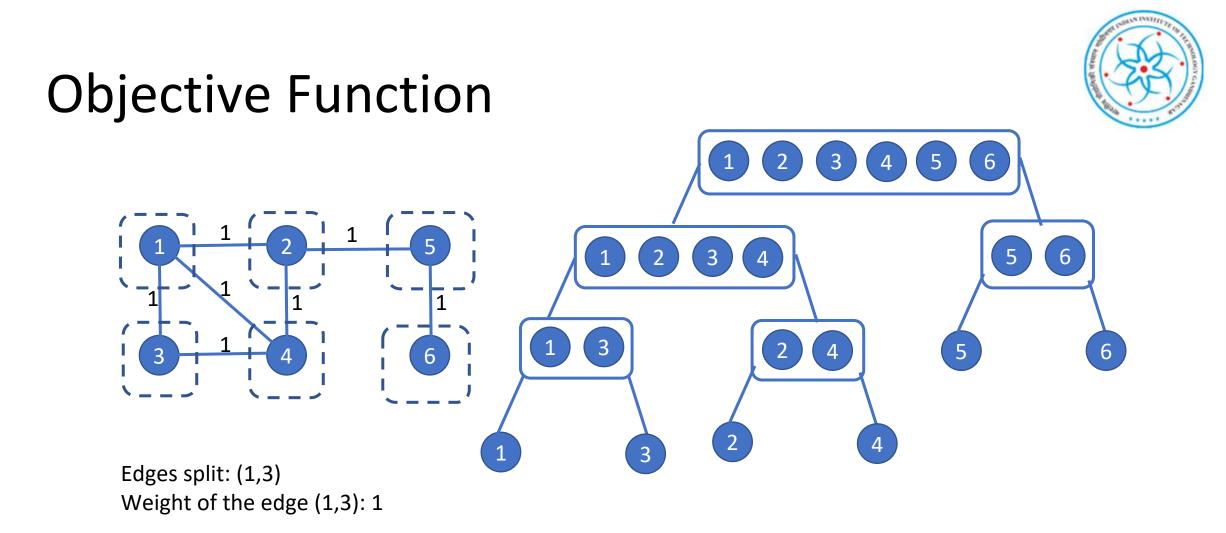
Cost: 1x2 = 2 Total Cost = 18 + 2 = 20



Edges split: (2,4) Weight of the edge (2,4): 1

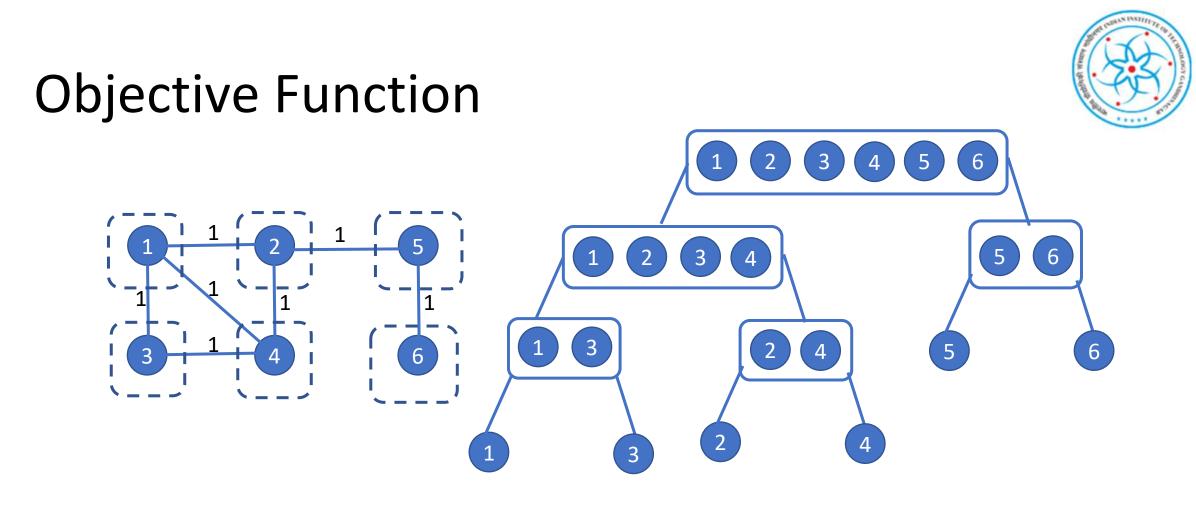
Number of nodes in cluster: 2

Cost: 1x2 = 2 Total Cost = 20 + 2 = 22



Number of nodes in cluster: 2

Cost: 1x2 = 2 Total Cost = 22 + 2 = 24



Total Cost = 24



- NP-Hard!
- Natural Greedy Criterion:
 - Sparsest cut at every internal node.



Sparsest Cut, Expansion and Conductance

For a graph $\mathcal{G}(V, E, w)$, if |S| denotes the number of elements in S, $E(S, \overline{S}) = \sum_{i \in S, j \in \overline{S}} w_{ij}$, and $vol(S) = \sum_{i,j \in S} w_{ij}$, then

Sparsest cut: $\sigma(S) = \frac{E(S,\overline{S})}{|S||\overline{S}|}, \qquad \sigma(G) = \min_{0 < |S| \le |V|/2} \sigma(S)$

Expansion:
$$\phi(S) = \frac{E(S,\overline{S})}{\min(|S|,|\overline{S}|)}, \quad \phi(G) = \min_{0 < |S| \le |V|/2} \phi(S)$$

Conductance: $\gamma(S) = \frac{E(S,\overline{S})}{\min(vol(S),vol(\overline{S}))}, \quad \gamma(G) = \min_{0 < |S| \le |V|/2} \gamma(S)$

[2] Trevisan, L. (2013). Lecture notes on expansion, sparsest cut, and spectral graph theory.

Sparsest Cut, Expansion and Conductance



Cheeger Inequality: If the graph \mathcal{G} is represented by the adjacency matrix \mathcal{C} , D is the degree matrix with $D_{ii} = \sum_j C_{ij}$ and we have $\tilde{C} = D^{-1/2}CD^{-1/2}$, if λ_2 is the second **largest** eigenvalue of \tilde{C} ,

$$\frac{1-\lambda_2}{2} \le \phi(\mathcal{G}) \le \sqrt{2(1-\lambda_2)}$$

[2] Trevisan, L. (2013). Lecture notes on expansion, sparsest cut, and spectral graph theory.

Splitting Rules



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- Related Work [1]
 - Based on Arora Rao Vazirani Algorithm for Sparsest Cut [3]
 - Quality: $O((\sqrt{\log n})OPT)$
 - Time: Õ (n⁴)
 - Based on Leighton Rao Algorithm for Sparsest Cut [4]
 - Quality: O((log n)OPT)
 - Time: O(n³)

[1] Dasgupta, S. (2015). A cost function for similarity-based hierarchical clustering. arXiv preprint arXiv:1510.05043.

[3] Arora, S., Rao, S., & Vazirani, U. (2009). Expander flows, geometric embeddings and graph partitioning. Journal of the ACM (JACM), 56(2), 5.

[4] Leighton, T., & Rao, S. (1999). Multicommodity max-flow min-cut theorems and their use in designing approximation algorithms. *Journal of the ACM (JACM)*, 46(6), 787-832.

Splitting Rules

- Our Work
 - Based on Eigenvectors for Sparsest Cut
 - Quality: O($n\Delta \log n \sqrt{OPT}$)
 - Time: O(min(nd², n²d))



 $\Delta = \text{deg}_{\text{max}}/\sqrt{\text{deg}_{\text{min}}}$

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Splitting Rules

- Our Work
 - Based on Eigenvectors for Sparsest Cut
 - Quality: O($n\Delta \log n \sqrt{OPT}$)
 - Time: O(min(nd², n²d))
 - Based on Approximate Eigenvectors for Sparsest Cut
 - Quality: O(n Δ log n $\sqrt{(OPT + \epsilon)}$)
 - Time: O(min(nd², n²d))

 $\Delta = \text{deg}_{\text{max}}/\sqrt{\text{deg}_{\text{min}}}$



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Splitting Rules

- Our Work
 - Based on Eigenvectors for Sparsest Cut
 - Quality: O($n\Delta \log n \sqrt{OPT}$)
 - Time: O(min(nd², n²d))
 - Based on Approximate Eigenvectors for Sparsest Cut
 - Quality: O(n Δ log n $\sqrt{(OPT + \varepsilon)}$)
 - Time: O(min(nd², n²d))
 - Based on Random Hyperplanes
 - Quality : O(n OPT) (Expected Cost)
 - Time : O(nd)

 $\Delta = \text{deg}_{\text{max}}/\sqrt{\text{deg}_{\text{min}}}$



Splitting Rules

- Our Work
 - Based on Eigenvectors for Sparsest Cut
 - Quality: O($n\Delta \log n \sqrt{OPT}$)
 - Time: O(min(nd², n²d))
 - Based on Approximate Eigenvectors for Sparsest Cut
 - Quality: O(n Δ log n $\sqrt{(OPT + \epsilon)}$)
 - Time: O(min(nd², n²d))
 - Based on Random Hyperplanes
 - Quality : O(n OPT) (Expected Cost)
 - Time : O(nd)
 - 2-Means
 - Quality : ??
 - Time: O(2nd)

 $\Delta = deg_{max}/V deg_{min}$

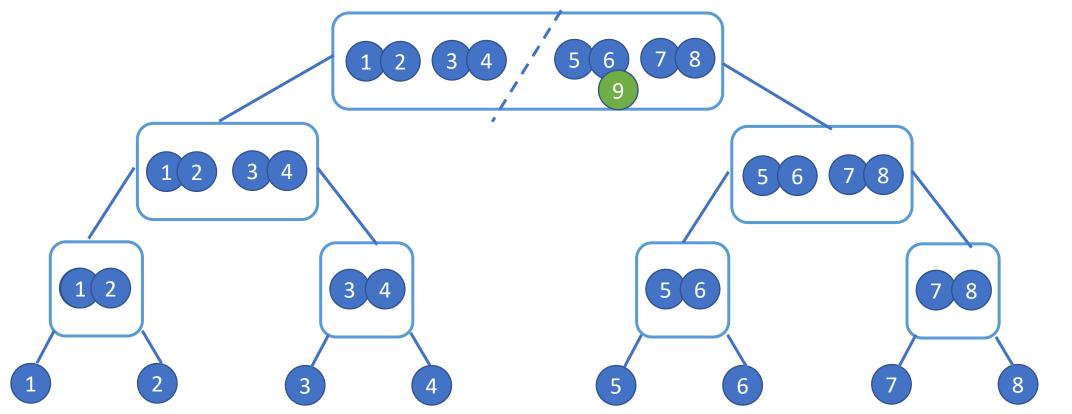


Implementation Details

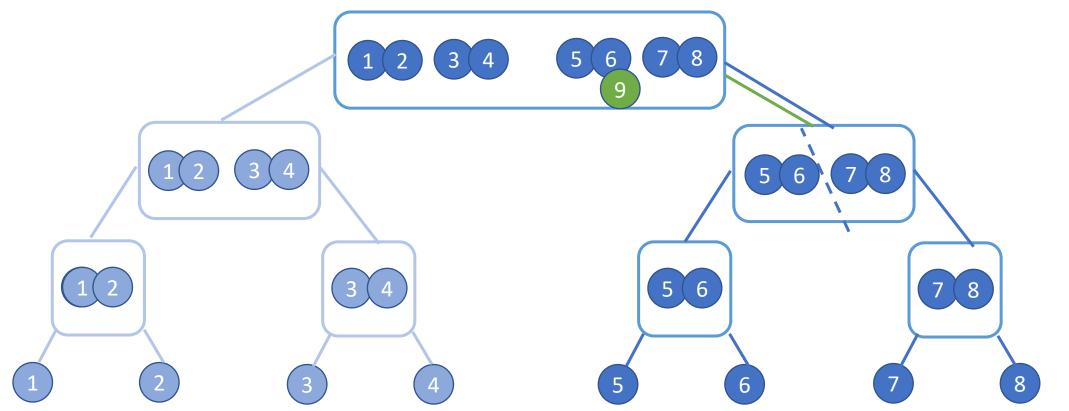


- Data, X, is normalized.
- Adjacency matrix created as X^TX.
- We work with (*nxd*) matrix D^{-1/2} X instead of D^{-1/2} X^TXD^{-1/2} which is *nxn*.
- Store the *d*-dimensional singular vector.
- Data is not normalized for large datasets.
- Balanced split point is chosen for practical reasons.



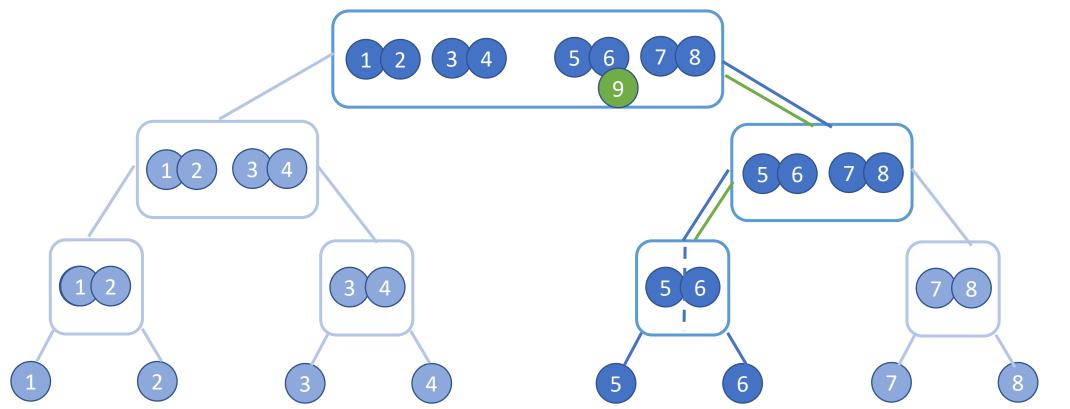






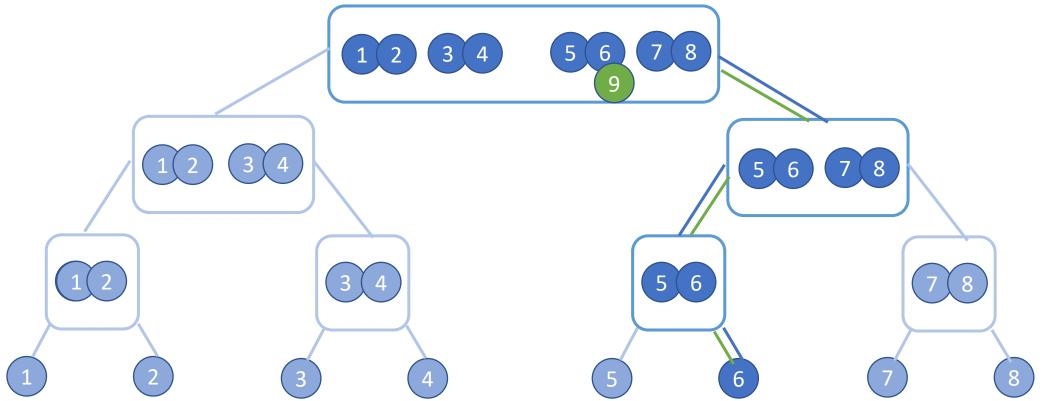








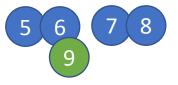






How do we find Nearest Neighbors

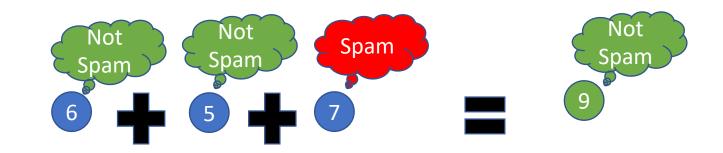
- Let Candidate Set Size be 4
- Returned points: 5 6 7 8
- Suppose we want 3 approximate nearest neighbors
- Calculate distance of 9 from each of 56 78
- Return the 3 closest ones, I.e., 6 5 7



Classification using the Hierarchy



- Fix some candidate set size, and number of nearest neighbors desired
- Traverse the tree and find the nearest neighbors
- All the points returned have a label associated with them
- Take the maximum vote among them





Classification Results

Dataset	Number of Classes	Dimensions	Train Size	Test Size
MNIST	10	784	60000	10000
ALOI	1000	128	88000	20000
CoverType	7	53	480102	100000
Comments (LinkedIn)	3	50	106537	20000

Comments Dataset



- 3 Classes
 - Spam: Content which is offensive, harmful, abusive or disruptive. These comments violate the Terms and Conditions of the networking site and are to be completely removed from the site.
 - Low-Quality: Content which is irrelevant to the discussion or unappealing. Such content may receive a diminished visibility on the site.
 - Clear: Content which is okay to receive unrestricted distribution on the site.
- Due to business requirements, treated as 2 binary classification problems.



Classification Results

	Method	MNIST Precision	Recall	F1-Score	Query Time	ALOI Precision	Recall	F1-Score	Query Time
Hierarchical	EV	0.93	0.929	0.93	0.702	0.893	0.889	0.891	0.701
Tree Based	AEV	0.924	0.924	0.924	0.729	0.893	0.890	0.891	0.690
Methods	RP	0.818	0.810	0.814	0.789	0.776	0.768	0.772	0.550
	2-means	0.929	0.929	0.929	1.243	0.892	0.889	0.890	0.97
Linkage	Single	0.114	0.955	0.204	~2k	0.036	0.670	0.069	~2k
	Average	0.100	0.999	0.182	~2k	0.001	0.971	0.002	~2k
	Complete	0.180	0.393	0.247	~2k	0.124	0.519	0.200	~2k
	Wards	0.548	0.602	0.574	~2k	0.393	0.562	0.463	~2k
	SVM	0.930	0.930	0.930	-	0.843	0.830	0.836	-
ANN	LSH	0.954	0.953	0.953	0.850	0.936	0.920	0.934	0.68
	Kd-Tree	0.969	0.968	0.968	540.38	0.949	0.948	0.948	22.30

Classification Results



Method	CoverType				Comments Clear vs (Lo	ts Low Quality + Spam)		Comments (Clear + Low Quality) vs Spam		
	Precision	Recall	F1-Score	Query Time	Precision	Recall	F1-Score	Precision	Recall	F1-Score
EV	0.925	0.921	0.923	0.380	0.750	0.840	0.80	0.739	0.740	0.740
AEV	0.925	0.922	0.923	0.370	0.760	0.840	0.80	0.738	0.740	0.740
RP	0.904	0.897	0.901	0.370	-	-	-	-	-	-
2-means	0.930	0.930	0.930	0.810	0.63	0.61	0.62	0.64	0.70	0.67
SVM	0.211	0.308	0.250	-	-	-	-	-	-	-
LSH	0.581	0.739	0.650	44.72	0.71	0.74	0.73	0.62	0.63	0.62
Kd-Tree	0.942	0.935	0.938	0.760	-	-	-	-	-	-

Anomaly Detection using the hierarchy



- Maintain a lookup table with class-wise average pairwise distances
- Classify the query (say C)
- Find the average distance of the query from the nearest neighbors, (say d1)
- Lookup average pairwise distance for C (say d2)
- If d2 + threshold < d1
 - Detect it as an anomaly
- Else
 - Report its' class



SVM as Baseline for Anomaly Detection

- Use prediction probability
- For a non-anomaly point, the prediction probability of its' actual class is high
- If prediction probability of the query < threshold
 - Detect it as anomaly
- Else
 - Report its' class



Anomaly Detection Results

Dataset Creation

- ALOI Dataset partitioned into two subsets
 - Train Set: 950 classes,
 - Test Set: 50 **new** classes + points from old classes

Dataset	Train Set Size	Test Set Size	Number of poin Unseen Class	ts from Seen Class
Dataset 1	92451	15549	5400	10149
Dataset 2	92443	15557	5400	10157
Dataset 3	92288	15712	5400	10312

Anomaly Detection Results



	Approx Eige Threshold	Approx EigenvectorSupport Vector MachineThresholdPrecisionRecallF1 ScoreThresholdPrecisionRecallF1				F1 Score		
Dataset 1	0.2	0.53	0.78	0.63	0.05	0.42	0.82	0.55
	0.3	0.58	0.66	0.61	0.08	0.42	0.76	0.54
	0.4	0.62	0.53	0.57	0.1	0.42	0.56	0.48
Dataset 2	0.2	0.53	0.80	0.64	0.05	0.42	0.84	0.56
	0.3	0.58	0.66	0.62	0.08	0.44	0.80	0.56
	0.4	0.63	0.54	0.58	0.1	0.45	0.61	0.52
Dataset 3	0.2	0.52	0.78	0.62	0.05	0.42	0.86	0.57
	0.3	0.57	0.67	0.62	0.08	0.43	0.78	0.55
	0.4	0.61	0.53	0.57	0.1	0.43	0.60	0.50



Requirements Satisfied

- Unsupervised 🗸
- Real-time classification \checkmark
- Incremental updates to the model imes
- Potentially use the subtype-supertype relationship \checkmark



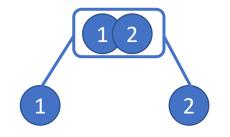
- Has the ability to perform incremental updates to the model.
- Recent work:
 - [1] proposed an algorithm based on bounding boxes called PERCH.
- Our work:
 - We propose two heuristics.

[5] Kobren, A., Monath, N., Krishnamurthy, A., & McCallum, A. (2017, August). A hierarchical algorithm for extreme clustering. In *Proceedings of the 23rd ACM SIGKDD* International Conference on Knowledge Discovery and Data Mining (pp. 255-264). ACM.

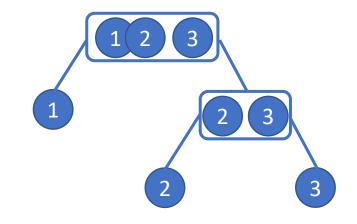




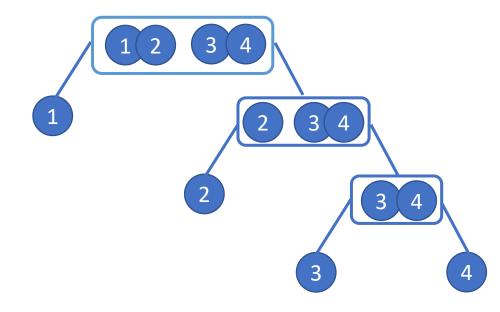




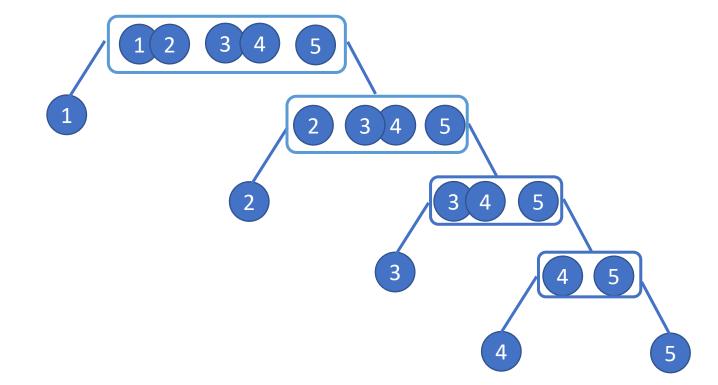








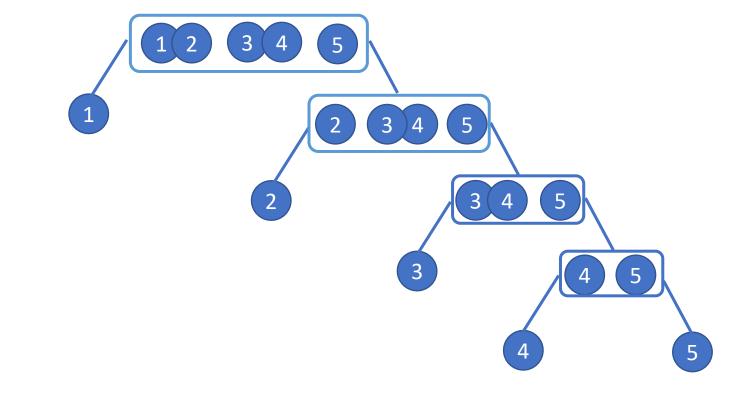


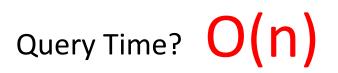




Query Time?







Doubling Heuristic



• Rebuild subtree when the number of points at root of subtree is doubled.

Balancing Heuristic



- Rebuild subtree when balance of subtree is distorted.
- Unbalanced if number of nodes in one side is more than double of nodes in the other side.

Results



Dataset	Doubling Heuristic			Balancing Heuristic			
	Precision	Recall	F1-Score	Precision	Recall	F1-Score	
MNIST	0.917	0.916	0.916	0.893	0.890	0.891	
ALOI	0.826	0.806	0.816	0.807	0.795	0.801	
CoverType	0.880	0.877	0.878	0.882	0.876	0.879	

Results



Method	(Clear + Low Quality) vs Spam			Clear vs (Low Quality + Spam)			
	Precision	Recall	F1-Score	Precision	Recall	F1-Score	
AEV	0.753	0.853	0.80	0.685	0.686	0.685	
PERCH	0.708	0.971	0.82	0.48	0.454	0.466	



Requirements Satisfied

- Unsupervised 🗸
- Real-time classification \checkmark
- Incremental updates to the model \checkmark
- Potentially use the subtype-supertype relationship \checkmark

Limitations



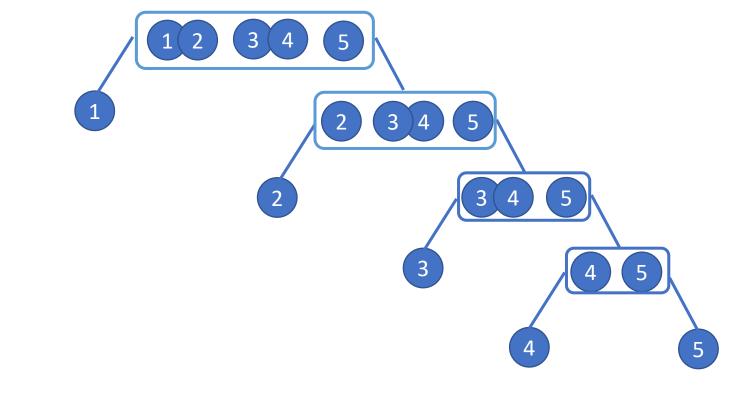
• No theoretical bound on the quality of the solution

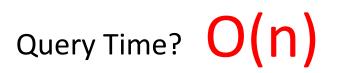
Next Steps



- Recall that we had a splitting strategy of using eigenvectors.
- Can we somehow update the eigenvectors in an online way?

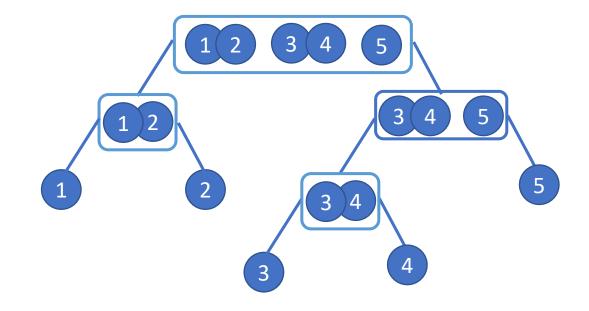








Online Hierarchical Clustering

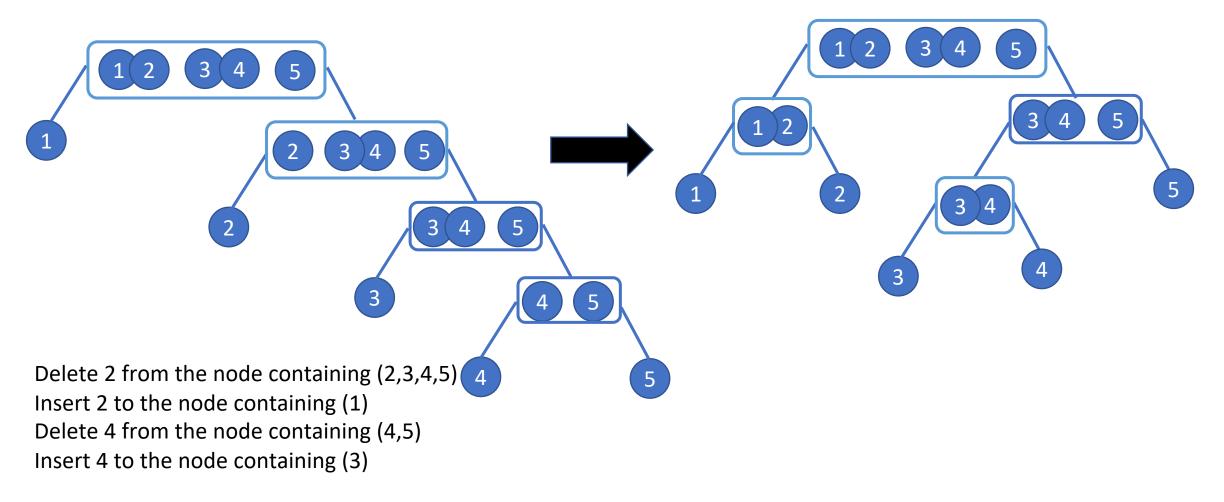


Logarithmic querying time

Points that are close are separated lower in the tree



Online Hierarchical Clustering



Next Steps



- Recall that we had a splitting strategy of using eigenvectors
- Can we somehow update the eigenvectors in a streaming way?
- But we need insertion and deletion of points!



Online Eigenvector Updates

- Partitioning in Dynamic Graphs
- Sensors
- Removal of Adversarial Inputs

Online Eigenvector Updates



- Related work when data is only inserted
 - Streaming PCA with limited memory, evaluated on the spiked covariance model [6].
 - Based on regret minimization [7].
 - Sub-sampling and dimensionality reduction [8,9].

[6] Mitliagkas, I., Caramanis, C., & Jain, P. (2013). Memory limited, streaming PCA. In Advances in Neural Information Processing Systems (pp. 2886-2894).

[7] Garber, D., Hazan, E., & Ma, T. (2015, July). Online Learning of Eigenvectors. In ICML (pp. 560-568).

[9] Halko, N., Martinsson, P. G., & Tropp, J. A. (2011). Finding structure with randomness: Probabilistic algorithms for constructing approximate matrix decompositions. SIAM review, 53(2), 217-288.

^[8] Clarkson, K. L., & Woodruff, D. P. (2009, May). Numerical linear algebra in the streaming model. In Proceedings of the forty-first annual ACM symposium on Theory of computing (pp. 205-214). ACM.



Orthogonal Dual Spiked Covariance Model

- Inspired by the Spiked Covariance Model [6]
- Insert from
 - $\mathbf{x}_t = \mathbf{u}\mathbf{z}_t + \mathbf{w}_t$
 - $\circ \mathbf{x}_{t} = \mathbf{v}\mathbf{z}_{t} + \mathbf{y}_{t}$
- Delete from
 - $\circ \mathbf{x}_{t} = \mathbf{v}_{z_{t}} + \mathbf{y}_{t}$

where $z_t \sim N(0,1)$, $w_t \sim N(0, \sigma_1^2 I)$, $y_t \sim N(0, \sigma_2^2 I)$

All z_t , w_t , y_t are mutually independent and $u^T v = v^T u = 0$.

[6] Mitliagkas, I., Caramanis, C., & Jain, P. (2013). Memory limited, streaming PCA. In Advances in Neural Information Processing Systems (pp. 2886-2894).

Algorithm

1: procedure INSERT (B, \mathbf{q}, λ)

- 2: $\mathbf{s} \leftarrow \mathbf{0}$
- 3: for $\mathbf{x_t} \in B$ do
- 4: $\mathbf{y} \leftarrow < \mathbf{q}, \mathbf{x_t} > \mathbf{x_t}$
- 5: $\mathbf{s} \leftarrow \mathbf{s} + \mathbf{y}$
- 6: $\lambda \leftarrow \lambda + < \mathbf{q}, \mathbf{y} >$
- 7: $\mathbf{s} \leftarrow \frac{1}{B}\mathbf{s}$
- 8: $\mathbf{q} \leftarrow \frac{\mathbf{s}}{||\mathbf{s}||_2}$ 9: return \mathbf{q}, λ

1: procedure $DELETE(B, \mathbf{q}, \lambda)$ 2: $\mathbf{s} \leftarrow 0$ 3: $\lambda_t \leftarrow 0$ 4: for $\mathbf{x_t} \in B$ do 5: $\mathbf{y} \leftarrow < \mathbf{q}, \mathbf{x_t} > \mathbf{x_t}$ 6: $\mathbf{s} \leftarrow \mathbf{s} + \mathbf{v}$

$$\lambda_t \leftarrow \lambda_t + < \mathbf{q}, \mathbf{y} >$$

$$\mathbf{s} \leftarrow \lambda \mathbf{q} - \mathbf{s}$$
$$\mathbf{q} \leftarrow \frac{\mathbf{s}}{||\mathbf{s}||_2}$$
$$\lambda \leftarrow \lambda - \lambda_t$$
$$\mathbf{return } \mathbf{q}, \lambda$$

7:

8:

9:

10:

11:

Theoretical Guarantees



 $\mathbf{q}_{\tau} = \sqrt{\alpha_{\tau}}\mathbf{u} + \sqrt{\gamma_{\tau}}\mathbf{v} + \sqrt{\delta_{\tau}}\mathbf{g}_{\tau}$ where \mathbf{g}_{τ} is orthogonal to both $\mathbf{u}, \mathbf{v}, \text{ and } \alpha_{\tau} + \gamma_{\tau} + \delta_{\tau} = 1$.

$$\alpha_{\tau} = (\mathbf{u}^{\mathbf{T}} \mathbf{q}_{\tau})^2 = \frac{(\mathbf{u}^{\mathbf{T}} \mathbf{s}_{\tau})^2}{||\mathbf{s}_{\tau}||_2^2}$$
$$\gamma_{\tau} = (\mathbf{v}^{\mathbf{T}} \mathbf{q}_{\tau})^2 = \frac{(\mathbf{v}^{\mathbf{T}} \mathbf{s}_{\tau})^2}{||\mathbf{s}_{\tau}||_2^2}$$
$$\delta_{\tau} = (\mathbf{g}_{\tau}^{\mathbf{T}} \mathbf{q}_{\tau})^2 = \frac{(\mathbf{g}_{\tau}^{\mathbf{T}} \mathbf{s}_{\tau})^2}{||\mathbf{s}_{\tau}||_2^2}$$

Insertion



Lemma 1.1. On insertion of a batch of points sampled from Model 1, the components along \mathbf{u} , \mathbf{v} and \mathbf{g}_{τ} change as:

$$\begin{aligned} \alpha_{\tau+1} &= \frac{\alpha_{\tau}(1+\sigma_1^2+\epsilon)^2}{(1+\sigma_1^2+\epsilon)^2 - (1-\alpha_{\tau})(1+2(\sigma_1^2+\epsilon))} \\ \gamma_{\tau+1} &= \frac{\gamma_{\tau}(\sigma_1^2+\epsilon)^2}{(\sigma_1^2+\epsilon)^2 + \alpha_{\tau}(1+2(\sigma_1^2+\epsilon))} \\ \delta_{\tau+1} &= \frac{\delta_{\tau}(\sigma_1^2+\epsilon)^2}{(\sigma_1^2+\epsilon)^2 + \alpha_{\tau}(1+2(\sigma_1^2+\epsilon))} \end{aligned}$$

Insertion



Lemma 1.2. On insertion of a batch of points sampled from Model 2, the components along \mathbf{u} , \mathbf{v} and \mathbf{g}_{τ} change as:

$$\begin{aligned} \alpha_{\tau+1} &= \frac{\alpha_{\tau}(\sigma_2^2 + \epsilon)^2}{(\sigma_2^2 + \epsilon)^2 + \gamma_{\tau}(1 + 2(\sigma_2^2 + \epsilon))} \\ \gamma_{\tau+1} &= \frac{\gamma_{\tau}(1 + \sigma_2^2 + \epsilon)^2}{(1 + \sigma_2^2 + \epsilon)^2 - (1 - \gamma_{\tau})(1 + 2(\sigma_2^2 + \epsilon))} \\ \delta_{\tau+1} &= \frac{\delta_{\tau}(\sigma_2^2 + \epsilon)^2}{(\sigma_2^2 + \epsilon)^2 + \gamma_{\tau}(1 + 2(\sigma_2^2 + \epsilon))} \end{aligned}$$

Deletion



Lemma 1.3. On deletion of a batch of points sampled from Model 2, the components along \mathbf{u} , \mathbf{v} and \mathbf{g}_{τ} change as:

$$\begin{aligned} \alpha_{\tau+1} &= \frac{\alpha_{\tau} (\lambda_{\tau} - B(\sigma_2^2 + \epsilon))^2}{(\lambda_{\tau} - B(\sigma_2^2 + \epsilon))^2 - \gamma_{\tau} (2B\lambda_{\tau} - B^2(1 + 2\sigma_2^2 + 2\epsilon))} \\ \gamma_{\tau+1} &= \frac{\gamma_{\tau} (\lambda_{\tau} - B(1 + \sigma_2^2 + \epsilon))^2}{(\lambda_{\tau} - B(1 + \sigma_2^2 + \epsilon))^2 + (1 - \gamma_{\tau})(B^2(1 + 2\sigma_2^2 + 2\epsilon) - 2B\lambda_{\tau})} \\ \delta_{\tau+1} &= \frac{\delta_{\tau} (\lambda_{\tau} - B(\sigma_2^2 + \epsilon))^2}{(\lambda_{\tau} - B(\sigma_2^2 + \epsilon))^2 - \gamma_{\tau} (2B\lambda_{\tau} - B^2(1 + 2\sigma_2^2 + 2\epsilon))} \end{aligned}$$

Theoretical Guarantee



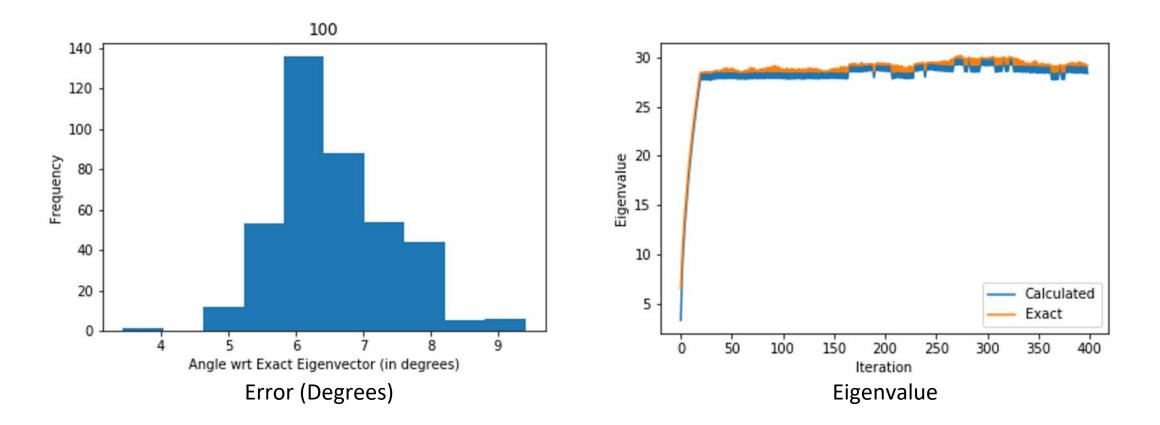
Theorem 1.4. For any batch of insertions or deletions,

$$\frac{\alpha_{\tau+1} + \delta_{\tau+1}}{\alpha_{\tau} + \delta_{\tau}} \le \frac{\alpha_{\tau+1}}{\alpha_{\tau}}$$

Results



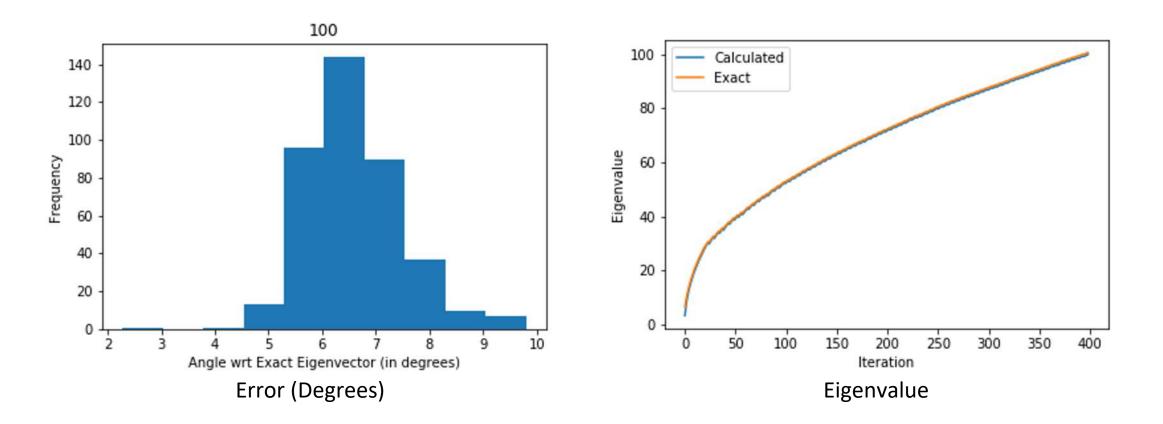
Batch Size = 100, 40k operations, Probability of Insertion = 0.5



Results



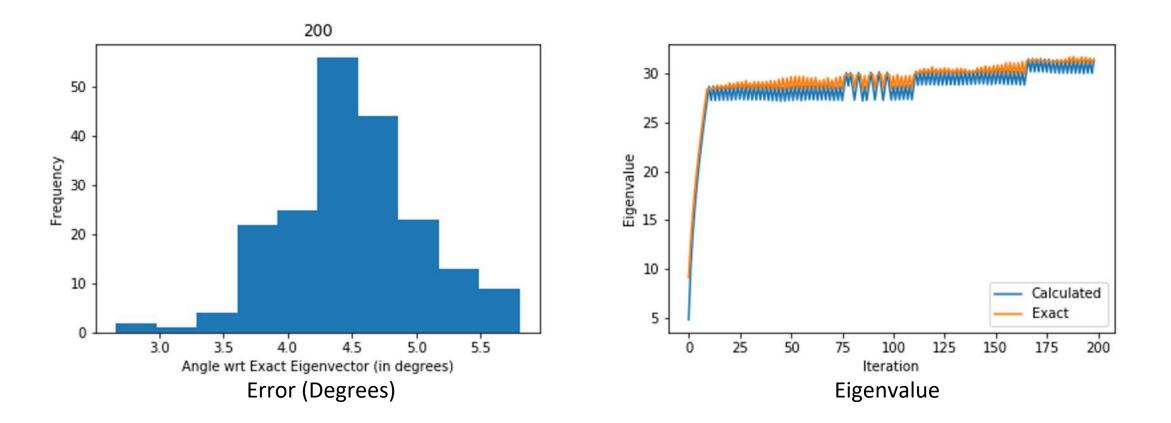
Batch Size = 100, 40k operations, Probability of Insertion = 0.8



Results



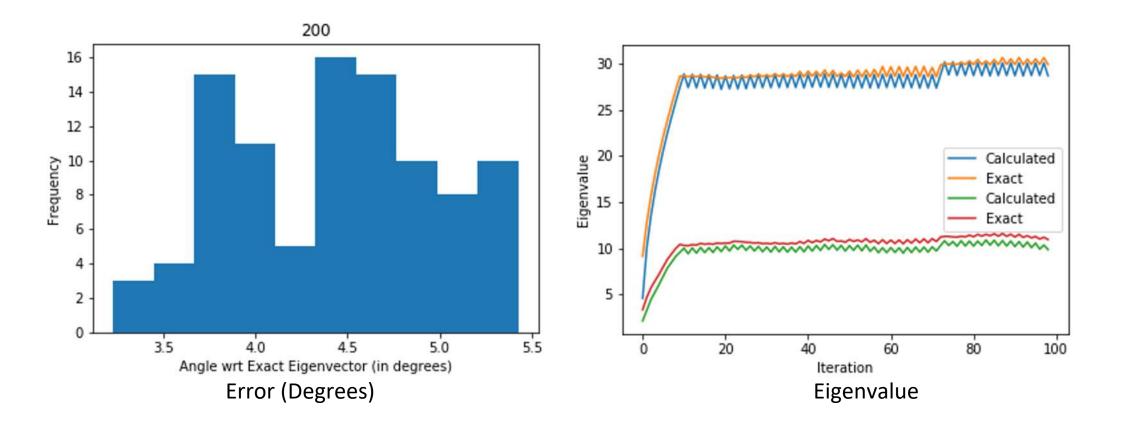
Batch Size = 200, 40k operations, Probability of Insertion = 0.5





Results - Rank 2

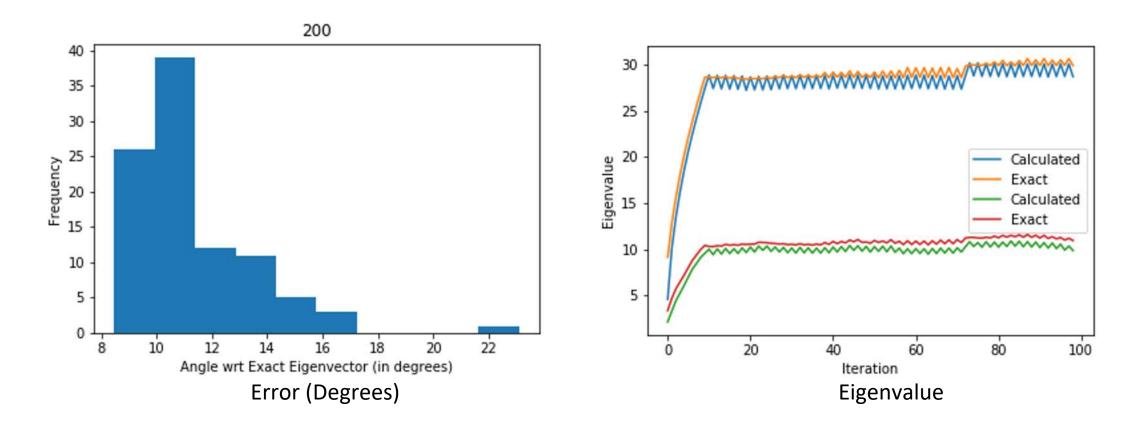
Batch Size = 200, 40k operations, Probability of Insertion = 0.5





Results - Rank 2

Batch Size = 200, 40k operations, Probability of Insertion = 0.5



Conclusion



- We propose three splitting rules for hierarchical clustering with guaranteed worst case performance.
- We propose two heuristics for Online Hierarchical Clustering.
- We identify and propose an algorithm for Online Eigenvector Updates.
- We evaluate the model on the *orthogonal dual spiked covariance model* and empirically on the MNIST dataset.

Future Work



- Generalize online eigenvector update results for rank-k case.
- Use them to obtain a bound on Online Hierarchical Clustering.
- Look at Distributed Hierarchical Clustering or Distributed Online Hierarchical Clustering problems.

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